

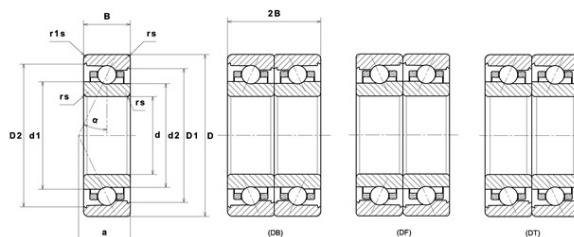
PDF technical sheet ML7001CVUJ74S



High precision angular contact ball bearings

High precision angular contact ball bearing, high speed series ML, laminated resin cage centred on outer ring

Product definition	
d	0.4724 "
D	1.1024 "
B	0.3150 "
d1	0.6555 "
d2	0.6122 "
D1	0.9035 "
D2	0.9350 "
a	0.2756 "
Contact angle, α	17 °
rs min	0.0118 "
r1s min	0.0118 "
f0	7.604
Precision class	P4S
Mass	0.07 oz
Brand	SNR



Product performance	
Dynamic load, C	2.26 kN
Static load, C0	0.95 kN
Fatigue limit load, Cu	0.06 kN
Nlim (oil)	110,000 RPM
Nlim (grease)	80,000 RPM
Axial displacement K Factor	2.25
Preload level	7
Peloid value	11 kN
axial rigidity	14 N/ μ m
radial rigidity	70 N/ μ m
Min operating temperature, Tmin	-22 °C
Max operating temperature, Tmax	248 °C
Characteristic cage frequency, FTF	0.42 Hz
Characteristic rolling element frequency, BSF	5.83 Hz
Characteristic outer ring frequency, BPF0	5.46 Hz
Characteristic inner ring frequency, BPF1	7.54 Hz



Abutment dimensions

da min	0.5709 "
db min	0.5709 "
Da max	1.0039 "
Db max	1.0039 "
r1a max	0.0118 "
ra max	0.0118 "
D6	0.7087 "

Calculation factors

Equivalent dynamic radial load

$$P = X \cdot Fr + Y \cdot Fa$$

Series			e	Single or DT bearing arrangement				DB or DF arrangement			
				Fa / Fr ≤ e		Fa / Fr > e		Fa / Fr ≤ e		Fa / Fr > e	
				X	Y	X	Y	X	Y	X	Y
70 (NTN & SNR) 72 (NTN & SNR) 78 (NTN) 79 (NTN) 719 (SNR)	15°	0.178	0.38	1	0	0.44	1.47	1	1.65	0.72	2.39
		0.357	0.4				1.4		1.57		2.28
		0.714	0.43				1.3		1.46		2.11
		1.07	0.46				1.23		1.38		2
		1.43	0.47				1.19		1.34		1.93
		2.14	0.5				1.12		1.26		1.82
		3.57	0.55				1.02		1.14		1.66
		5.35	0.56						1.12		1.63
		7.14	0.56				1		1.12		1.63
	25°		0.68			0.41	0.87		0.92	0.67	1.41
	30°		0.8				0.39		0.78		1.24

Equivalent static radial load

$$P_0 = X_0 \cdot Fr + Y_0 \cdot Fa$$

Series			Single or DT bearing arrangement		DB or DF arrangement	
			X ₀	Y ₀	X ₀	Y ₀
70 (NTN & SNR) 72 (NTN & SNR) 78 (NTN) 79 (NTN) 719 (SNR)	15°		0.5	0.46	1	0.92
	25°			0.38		0.76
	30°			0.33		0.66

For single or DT bearing arrangement :

If $P_0 < Fr$, then use $P_0 = Fr$